

DESIGN OF A MECHATRONIC MODULE MEASURING THE VISCOSITY OF SOLUBLE AND LIQUID PRODUCTS

Oybek Kholmatov

Senior Teacher, Andijan Machine-Building Institute,
Uzbekistan, Andijan

Zaynobiddinov Khojiakbar

Student, Andijan Machine-Building Institute,
Uzbekistan, Andijan

E-mail: holmatov.oybek@bk.ru

Abstract

This note provides detailed information on the design and functionality of a mechatronic module designed to accurately measure the viscosity of soluble and liquid products under industrial conditions [1]. Combining mechanical, electrical and computational elements, this innovative module offers real-time analysis, control and data visualization capabilities. Key design issues are explored, including sensor selection, actuation mechanisms, material compatibility, and data acquisition techniques [2]. The statement also emphasizes the module's versatility and application in various fields, highlighting innovative features such as modular architecture, self-calibration mechanisms, user-friendly interfaces and connectivity options. Through this commentary, readers will gain insight into the transformative potential of mechatronic solutions to improve product quality, optimize processes, and drive innovation in industrial manufacturing [3].

Keywords: Mechatronic module, Viscosity measurement, soluble products, Liquid products, industrial tools, Sensor technology, Actuation mechanisms, Material compatibility, Data acquisition, real-time analysis, Control systems, Modular design, User interface, Connectivity, Precision engineering, Process optimization, Quality control, Industrial automation, Manufacturing innovation.

Introduction

Viscosity measurement plays an important role in ensuring the quality and efficiency of industrial production processes in various fields. In the food and beverage, pharmaceutical, cosmetic, chemical, and other industries, the viscosity of soluble solutions and liquid formulations directly affects product performance, customer satisfaction, and operating costs. The value of viscosity measurement lies in its ability to provide invaluable insights into fluid behavior, consistency, and performance [4]. For example, in the food and beverage industry, viscosity measurement helps maintain the desired texture and mouthfeel in products such as sauces, beverages, and dairy products. Viscosity control in pharmaceutical manufacturing is essential for the correct dosing and administration of drugs, as well as for the stability of suspensions and emulsions. Similarly, in chemical processing, viscosity measurement is essential to optimize the flow properties of raw materials and finished products, thereby



increasing process efficiency and reducing waste. Traditionally, viscosity measurement has relied on manual techniques or stand-alone instruments that provide limited functionality and accuracy. However, with advances in mechatronics, a multidisciplinary field that combines mechanical, electrical, and computer engineering, manufacturers now have integrated solutions capable of delivering real-time viscosity data with unprecedented accuracy and reliability. Mechatronic modules for viscosity measurement seamlessly integrate mechanical components such as sensors, actuators and pumps with electronic control systems and data processing algorithms [5]. This integration enables dynamic fluid flow control, automated measurement processes, and instant feedback for process optimization. In addition, mechatronic modules offer versatility in terms of application and scalability, allowing seamless integration into existing production lines or customization for specific production requirements. The innovative design of mechatronic modules for viscosity measurement represents a paradigm shift in industrial instrumentation. By harnessing the power of mechatronics, manufacturers can achieve higher levels of product quality, consistency and efficiency, resulting in competitiveness and innovation in today's dynamic market landscape. As the industry continues to evolve, the adoption of mechatronic solutions is poised to revolutionize the practice of viscosity measurement, ushering in a new era of excellence in industrial manufacturing [6].

Methods

The method begins with a comprehensive research and analysis of the requirements and problems associated with viscosity measurement in industrial production. This step involves reviewing existing literature, industry standards, and best practices to identify key parameters and considerations. Based on the results of the study, the specific requirements for the mechatronic module are determined, including the range of measurable viscosity, types of soluble and liquid products, environmental conditions and regulatory standards [7].

The conceptual design of the mechatronic module is developed through brainstorming sessions, feasibility studies and preliminary design sketches. Emphasis is placed on integrating innovative features and technologies to increase functionality and efficiency. Component selection involves careful selection of sensors, actuators, pumps, valves, and materials based on factors such as accuracy, reliability, compatibility, and cost-effectiveness [8].

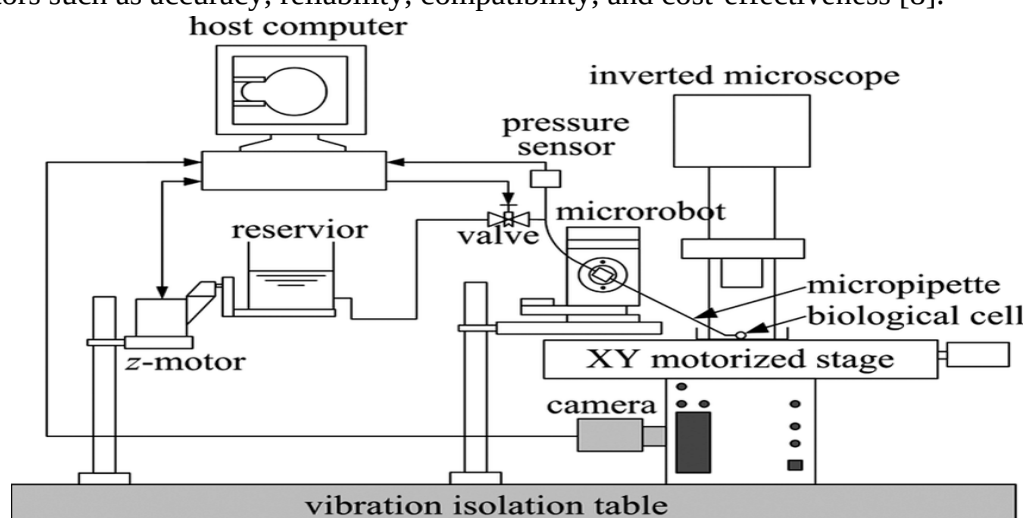


Figure-1. Schematic diagram of the micropipette aspiration system

After the components are selected, a detailed design of the mechatronic module is created, including CAD models, engineering drawings, and schematics showing the arrangement, dimensions, and relationships of the components. Special attention is paid to mechanical tolerances, electrical interfaces and fluid dynamics to ensure seamless integration and functionality [9].

A prototype mechatronic module is then manufactured and assembled, undergoing rigorous testing and inspection to ensure that it meets predetermined requirements and specifications. This includes performance tests under various operating conditions, calibration of sensors and actuators, verification of data accuracy, reliability and durability evaluation.

Iterative improvements and optimizations are made to the design and functionality of the module based on test results and feedback. This iterative process may involve several stages of testing, redesigning, and validating until the module achieves the desired level of performance, reliability, and usability [10].

When a mechatronic module meets the specified criteria, comprehensive documentation is produced, including user manuals, specifications, and maintenance procedures. The module is then deployed for field testing or integration into industrial production processes, with ongoing support and training provided as needed [11].

Conclusion:

The design of a mechatronic module for measuring the viscosity of soluble and liquid products represents a significant leap forward in industrial instrumentation. This innovative solution offers unprecedented accuracy, reliability and versatility in viscosity measurement through the seamless integration of mechanical, electrical and computational elements.

Through careful research, conceptualization and iterative improvement, the mechatronic module is designed to meet the various needs of industrial production in various fields. Its ability to analyze, monitor and visualize data in real-time allows manufacturers to optimize processes, improve product quality and drive innovation.

In addition, the modular architecture, self-calibration mechanisms, user-friendly interface and connectivity options built into the module emphasize its flexibility and ease of integration into existing production lines. This simplifies and future-proofs module implementation for changing industry requirements.

As the industry continues to evolve and demand higher standards of efficiency and quality, the adoption of mechatronic modules for viscosity measurement is expected to increase. By leveraging these advanced technologies, manufacturers can stay ahead of the curve, increase their competitiveness, and usher in a new era of excellence in industrial manufacturing.

References

1. Xolmatov Oybek Olim o'g'li, & Xoliqov Izzatulla Abdumalik o'g'li. (2023). QUYOSH PANELI YUZASINI TOZALOVCHI MOBILE ROBOTI TAXLILI. *Innovations in Technology and Science Education*, 2(7), 791–800.
URL:<https://humoscience.com/index.php/itse/article/view/424>
2. Xolmatov Oybek Olim o'g'li, & Vorisov Raxmatulloh Zafarjon o'g'li. (2023). KALAVA IPI ISHLAB CHIQRISHDA PAXTANI SIFATINI NAZORAT QILISH



MUAMMOLARINING TAXLILI. *Innovations in Technology and Science Education*, 2(7), 801–810.

URL: <https://humoscience.com/index.php/itse/article/view/425>

3. Холматов Ойбек Олим угли, & Иминов Холмуродбек Элмуродбек угли. (2023). ЭКСТРАКЦИЯ ХЛОПКОВОГО МАСЛА С ИСПОЛЬЗОВАНИЕМ ТЕХНОЛОГИИ СУБКРИТИЧЕСКОЙ ВОДЫ. ЭКСТРАКЦИЯ ХЛОПКОВОГО МАСЛА С ИСПОЛЬЗОВАНИЕМ ТЕХНОЛОГИИ СУБКРИТИЧЕСКОЙ ВОДЫ. *Innovations in Technology and Science Education*, 2(7), 852–860.

URL: <https://humoscience.com/index.php/itse/article/view/432>

4. Холматов Ойбек Олим угли, & Хасанов Жамолиддин Фазлитдин угли. (2023). АВТОМАТИЧЕСКАЯ СИСТЕМА ОЧИСТКИ СОЛНЕЧНЫХ ПАНЕЛЕЙ НА БАЗЕ ARDUINO ДЛЯ УДАЛЕНИЯ ПЫЛИ. *Innovations in Technology and Science Education*, 2(7), 861–871.

URL: <https://humoscience.com/index.php/itse/article/view/433>

5. Xolmatov Oybek Olim o'g'li, & Jo'rayev Zoxidjon Azimjon o'g'li. (2023). MACHINE LEARNING YORDAMIDA IDISHNI SATHINI ANIQLASH. *Innovations in Technology and Science Education*, 2(7), 1163–1170.

URL: <https://humoscience.com/index.php/itse/article/view/477>

6. Холматов О.О., Муталипов Ф.У. “Создание пожарного мини-автомобиля на платформе Arduino” *Universum: технические науки : электрон. научн. журн.* 2021. 2(83).

URL: <https://7universum.com/ru/tech/archive/item/11307>

7. Холматов О.О., Дарвишев А.Б. “Автоматизация умного дома на основе различных датчиков и Arduino в качестве главного контроллера” *Universum: технические науки : электрон. научн. журн.* 2020. 12(81).

URL: <https://7universum.com/ru/tech/archive/item/11068>

DOI:10.32743/UniTech.2020.81.12-1.25-28

8. Холматов О.О., Бурхонов З.А. “ПРОЕКТЫ ИННОВАЦИОННЫХ ПАРКОВОК ДЛЯ АВТОМОБИЛЕЙ” *Международный научный журнал «Вестник науки» № 12 (21) Том 4 ДЕКАБРЬ 2019 г.*

URL: <https://www.elibrary.ru/item.asp?id=41526101>

9. Kholmatov O.O., Burkhonov Z., Akramova G. “THE SEARCH FOR OPTIMAL CONDITIONS FOR MACHINING COMPOSITE MATERIALS” *science and world International scientific journal*, №1(77), 2020, Vol.I

URL: http://en.scienceph.ru/f/science_and_world_no_1_77_january_vol_i.pdf#page=28

10. Холматов О.О, Бурхонов З, Акрамова Г “АВТОМАТИЗАЦИЯ И УПРАВЛЕНИЕ ПРОМЫШЛЕННЫМИ РОБОТАМИ НА ПЛАТФОРМЕ ARDUINO” *science and education scientific journal volume #1 ISSUE #2 MAY 2020*

URL: <https://www.openscience.uz/index.php/sciedu/article/view/389>

11. Кабулов Н. А., Холматов О.О “AUTOMATION PROCESSING OF HYDROTHERMIC PROCESSES FOR GRAINS” *Universum: технические науки журнал декабрь 2021 Выпуск: 12(93) DOI - 10.32743/UniTech.2021.93.12.12841*

URL: <https://7universum.com/ru/tech/archive/item/12841>

DOI - 10.32743/UniTech.2021.93.12.12841



12. Холматов О.О., Негматов Б.Б “РАЗРАБОТКА И ВНЕДРЕНИЕ ИНТЕЛЛЕКТУАЛЬНОЙ СИСТЕМЫ УПРАВЛЕНИЯ СВЕТОФОРОМ С БЕСПРОВОДНЫМ УПРАВЛЕНИЕМ ОТ ARDUINO” *Universum: технические науки: научный журнал*, – № 6(87). июнь, 2021 г.

URL: <https://7universum.com/ru/tech/archive/item/11943>

DOI-10.32743/UniTech.2021.87.6.11943.

13. Холматов О.О., Негматов Б.Б “АВТОМАТИЗАЦИЯ ПРОЦЕССА ОБРАБОТКИ ЗЕРНА” *Universum: технические науки: научный журнал*. – № 3(96). Часть 1. М., Изд. «МЦНО», 2022 г.

URL: <https://7universum.com/ru/tech/archive/item/13235>

DOI - 10.32743/UniTech.2022.96.3.13235

14. Холматов Ойбек Олим угли “АВТОМАТИЗАЦИЯ СИСТЕМЫ ЗЕРНОВЫХ ОСУШИТЕЛЕЙ С ПОМОЩЬЮ ПЛК” *Universum: технические науки: научный журнал*. – № 3(96). Часть 1. М., Изд. «МЦНО», 2022 г.

URL: <https://7universum.com/ru/tech/archive/item/13234>

DOI - 10.32743/UniTech.2022.96.3.13234

15. Холматов Ойбек Олим угли, & Негматов Бегзодбек Баходир угли. (2022). МЕТОДЫ ОРГАНИЗАЦИИ ЛОГИСТИЧЕСКИХ УСЛУГ С ИСПОЛЬЗОВАНИЕМ ИНТЕЛЛЕКТУАЛЬНЫХ СИСТЕМ ОРГАНИЗАЦИИ ГРУЗОВ. *E Conference Zone*, 219–221.

URL: <https://econferencezone.org/index.php/ecz/article/view/196>

16. Kholmatorov Oybek Olim ugli, & Negmatov Begzodbek Bakhodir ugli. (2022). OPTIMIZATION OF AN INTELLIGENT SUPPLY CHAIN MANAGEMENT SYSTEM BASED ON A WIRELESS SENSOR NETWORK AND RFID TECHNOLOGY. *E Conference Zone*, 189–192.

URL: <http://www.econferencezone.org/index.php/ecz/article/view/467>

17. Мацко Ольга, Холматов Ойбек, & Думахонов Фуркатбек. ПРОЕКТИРОВАНИЕ РОБОТА МАНИПУЛЯТОРА С ОГРАНИЧЕННЫМИ УГЛАМИ ПЕРЕДВИЖЕНИЯ НА ПРИНЦИПЕ РАБОТЫ СЕРВОДВИГАТЕЛЯ В ПРОГРАММНОМ ОБЕСПЕЧЕНИИ ARDUINO И PROTEUS. *UNIVERSAL JOURNAL OF TECHNOLOGY AND INNOVATION*, 1(1), 28–40.

URL: <https://humoscience.com/index.php/ti/article/view/1174>

18. Мацко Ольга Николаевна, Холматов Ойбек, & Думахонов Фуркатбек. РАЗРАБОТКА СИСТЕМ АВТОМАТИЧЕСКОГО УПРАВЛЕНИЯ ДЛЯ ТЕПЛИЧНЫХ СООРУЖЕНИЙ НА ПОГОДНЫХ УСЛОВИЯХ СЕВЕРНОГО ПОЛЮСА. *UNIVERSAL JOURNAL OF ACADEMIC AND MULTIDISCIPLINARY RESEARCH*, 1(1), 75–88.

URL: <https://humoscience.com/index.php/amr/article/view/1115>

19. XOLMATOV, O. (2022). AUTOMATION OF GRAIN PROCESSING. *Universum: технические науки*. [https://doi.org/DOI - 10.32743/UniTech.2022.96.3.13235](https://doi.org/DOI-10.32743/UniTech.2022.96.3.13235)

20. XOLMATOV, O. (2022). AUTOMATION OF GRAIN DRYER SYSTEM USING PLC. *Universum: технические науки*. [https://doi.org/DOI - 10.32743/UniTech.2022.96.3.13234](https://doi.org/DOI-10.32743/UniTech.2022.96.3.13234)



21. Alijon o'g'li, E. O., & Sodiq o'g'li, M. U. (2024). Uarm robots in python data base formation electrical principle and structure scheme design. European Journal of Emerging Technology and Discoveries, 2(2), 43-47.
URL:<https://humoscience.com/index.php/itse/article/view/42>
22. Alijon o'g'li, E. O. (2023). Robototexnik tizmlarning tashqi ob'ektlarga ta'sir ko'rsatishida gidroyuritmalardan foydalanish usullari. Mexatronika va robototexnika: muammolar va rivojlantirish istiqbollari, 1(1), 102-104.
URL:<https://humoscience.com/index.php/itse/article/view/43>
23. Ergashev, O. A. O. G. L. (2022). Robototexnik tizimlarning tashqi obyektlarga ta'sir ko'rsatishida suyuqlik oqimlaridan foydalanish usullarini tadqiq etish. Science and Education, 3(6), 399-402.
URL:<https://humoscience.com/index.php/itse/article/view/44>
24. Tokhirov, A. I. (2021). USING THE GRAPHICAL EDITOR" КОМПАС 3D" in teaching computer engineering graphics. Universum: технические науки: электрон. научн. журн, 7(88), 8-3.
25. Tokhirov, A. (2021). Application procedure CAD/CAM/CAE-systems in scientific research. Universum: технические науки, (6-5), 16-19.
26. Tokhirov, A. (2021). Writing control programs for computer numeral control machines. Universum: технические науки, (5-6), 15-17.
27. Tokhirov, A. (2021). WRITING CONTROL PROGRAMS FOR COMPUTER NUMERAL CONTROL MACHINES. Universum: технические науки, (5-6), 15-17.
28. ugli Tokhirov, A. I. (2021). Technological process development using CAD-CAM programs. Science and Education, 2(6), 288-291.
29. Tokhirov, A. I. U. (2021). Technological process development using CAD-CAM programs. Science and Education, 2(6), 288-291.
30. TOKHIROV, A., & MARASULOV, I. (2021). Control models and information system of cotton storage in the claster system. UNIVERSUM, 12-18.
31. Ogli, I. M. R., & Ogli, T. A. I. (2021). A Role of Mechanical Engineering in Mechatronics. JournalNX, 824-828.
32. Djurayev, A. D., Tokhirov, A. I., & Marasulov, I. R. (2022). CLEANING COTTON FROM SMALL DIRTY. Universum: технические науки: электрон. научн. журн, 3, 96.
33. A'zamjon, T. (2022). ROBOTOTEXNIKA MAJMUALARINING AVTOMATLASHTIRILGAN ELEKTR YURITMALARINI QO'LLANILISH SOHALARI. Involta Scientific Journal, 1(6), 3-9.
34. A'zamjon, T. (2022). ROBOTOTEXNIKA MAJMUALARINING AVTOMATLASHTIRILGAN ELEKTR YURITMALARINI QO'LLANILISH SOHALARI. Involta Scientific Journal, 1(6), 3-9.
35. Marasulov, I. R., & Toxirov, A. I. (2021). A role of mechanical engineering in mechatronics. Journal NX—A Multidisciplinary Peer Reviewed Journal, 824-828.
36. Tokhirov, A. I. Methodology of teaching three-dimen modeling using the program «КОМПАС 3D». Eurasian Journal of Academic research Innovative Academy Research Support Center/[Электронный ресурс].—Режим доступа: <https://doi.org/10.5281/zenodo.4718298>.



37. Tokhirov, A. (2021). APPLICATION PROCEDURE CAD (No. 6, p. 87). CAM/CAE–SYSTEMS IN SCIENTIFIC RESEARCH//Universum: technical sciences: a scientific journal.
38. Ibrohim o'g, T. A. Z. (2022). Robototechnics And Technical Sets Application Of Automatic Electric Power Supplies Fields. Open Access Repository, 8(6), 92-96.
39. Джураев, А. Д., Далиев, Ш. Л., & Тохиров, А. И. У. (2022). РАЗРАБОТКА ЭФФЕКТИВНОЙ КОНСТРУКТИВНОЙ СХЕМЫ ОЧИСТИТЕЛЯ ХЛОПКА-СЫРЦА ОТ МЕЛКОГО СОПА. Universum: технические науки, (9-2 (102)), 26-28.
40. Anvar, D., Azamjon, T., & Islombek, M. (2022). CLEANING COTTON FROM SMALL DIRTY. Universum: технические науки, (3-7 (96)), 9-14.
41. Azamjon, T., & Islombek, M. (2021). CONTROL MODELS AND INFORMATION SYSTEM OF COTTON STORAGE IN THE CLASTER SYSTEM. Universum: технические науки, (11-6 (92)), 12-18.
42. Azamjon, T. (2021). WRITING CONTROL PROGRAMS FOR COMPUTER NUMERAL CONTROL MACHINES. Universum: технические науки, (5-6 (86)), 15-17.
43. Ugli, T. A. I. (2021). USING THE GRAPHICAL EDITOR" КОМПАС 3D" IN TEACHING COMPUTER ENGINEERING GRAPHICS. Universum: технические науки, (7-3 (88)), 38-43.
44. Azamjon, T. (2021). APPLICATION PROCEDURE CAD/CAM/CAE-SYSTEMS IN SCIENTIFIC RESEARCH. Universum: технические науки, (6-5 (87)), 16-19.
45. IR, D. A. T. A. M. CLEANING COTTON FROM SMALL DIRTY.
46. A'zamjon Ibrohim o'g'li Toxirov, Robototexnika majmualarining avtomatlashtirilgan elektr yuritmalarini qo'llanilish sohalari, "Science and Education" Scientific Journal, May 2022 Vol. 3 No. 5 (2022): Science and Education
URL: <https://openscience.uz/index.php/sciedu/article/view/3425>
47. Toxirov A'zamjon. ROBOTOTEXNIKA MAJMUALARINING AVTOMATLASHTIRILGAN ELEKTR YURITMALARINI QO'LLANILISH SOHALARI. *Involta Scientific Journal*, 1(6), 3–9.
URL: <https://involta.uz/index.php/iv/article/view/159>
DOI - 10.5281/zenodo.6519792
48. Djurayev A.D., Tokhirov A.I., Marasulov I.R. CLEANING COTTON FROM SMALL DIRTY // Universum: технические науки : электрон. научн. журн. 2022. 3(96).
URL: <https://7universum.com/ru/tech/archive/item/13196>
DOI - 10.32743/UniTech.2022.96.3.13196
49. Tokhirov A.I. Writing control programs for computer numeral control machines // Universum: технические науки : электрон. научн. журн. 2021. 5(86).
URL: <https://7universum.com/ru/tech/archive/item/11810>
DOI - 10.32743/UniTech.2021.86.5.11810
50. Tokhirov A.I. Application procedure CAD/CAM/CAE - systems in scientific research // Universum: технические науки : электрон. научн. журн. 2021. 6(87).
URL: <https://7universum.com/ru/tech/archive/item/11836>
DOI - 10.32743/UniTech.2021.87.6.11836
51. Tokhirov A.I. Using the graphical editor "Компас 3D" in teaching computer engineering graphics // Universum: технические науки : электрон. научн. журн. 2021. 7(88).



URL: <https://7universum.com/ru/tech/archive/item/12076>

DOI: 10.32743/UniTech.2021.78.8-3.12076

52. Tokhirov A.I., Marasulov I.R. CONTROL MODELS AND INFORMATION SYSTEM OF COTTON STORAGE IN THE CLUSTER SYSTEM // Universum: технические науки : электрон. научн. журн. 2021. 11(92).

URL: <https://7universum.com/ru/tech/archive/item/12486>

53. Azamjon Ibrohim ugli Tokhirov, "TECHNOLOGICAL PROCESS DEVELOPMENT USING CAD-CAM PROGRAMS", "Science and Education" Scientific Journal, June 2021

URL: <https://openscience.uz/index.php/sciedu/article/view/1561>

54. Toxirov A'zamjon Ibrohim o'g'li, "METHODOLOGY OF TEACHING THREE-DIMEN MODELING USING THE PROGRAM "KOMPAS-3D"", EURASIAN JOURNAL OF ACADEMIC RESEARCH Innovative Academy Research Support Center,

URL: <https://doi.org/10.5281/zenodo.4718298>

55. Marasulov Islombek Ravshanbek o'g'li, Tohirov A'zamjon Ibrohim o'g'li, "THE IMPORTANCE OF AUTOMATION OF COTTON RECEIVING SYSTEM", EURASIAN JOURNAL OF ACADEMIC RESEARCH Innovative Academy Research Support Center,

URL: <https://doi.org/10.5281/zenodo.4898919>

56. Toxirov A'zamjon Ibrohim o'g'li, "QUALITY IN MODERN MANUFACTURING ENTERPRISES THE ROLE OF ROBOTOTECHNICS AND AUTOMATED ELECTRICAL INSTRUMENTS IN PRODUCTION", EURASIAN JOURNAL OF ACADEMIC RESEARCH Innovative Academy Research Support Center,

URL: <https://doi.org/10.5281/zenodo.4968770>

57. Islombek Marasulov Ravshanbek Ogli, & Toxirov Azamjon Ibrohim Ogli. (2021). A ROLE OF MECHANICAL ENGINEERING IN MECHATRONICS. *JournalNX - A Multidisciplinary Peer Reviewed Journal*, 824–828.

URL: <https://repo.journalnx.com/index.php/nx/article/view/1690>.

